Math 2550-04 9/30/24

(Topic 4 continued ...) Last time we showed how to Write a system of linear equations in the form AX=b If A exists then we will be able to solve for x as follows: A = b $A^{-\prime}A^{-\prime}X = A^{-\prime}b$ To $T_n \dot{x} = A^{-1}b$ $\vec{X} = A^{-1} \vec{b}$ So, if A'exists there will be one solution to the system.

EX: Solue 3× +3Z=9 x + y + 2z = -4 (\mathbf{X}) = 5 -2x+3y Write it as AX=b like this: $\begin{pmatrix} 3 & 0 & 3 \\ 1 & 1 & 2 \\ -2 & 3 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 9 \\ -4 \\ 5 \end{pmatrix}$ Check: If you multiply the left $\begin{pmatrix} 3x + 3z \\ x + y + 2z \\ -2x + 3y \end{pmatrix} = \begin{pmatrix} 9 \\ -4 \\ 5 \end{pmatrix} 4 \qquad Same as \\ system$ Side you get:

Rewriting we have

$$\begin{pmatrix} 3 & 0 & 3 \\ 1 & 1 & 2 \\ -2 & 3 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 9 \\ -4 \\ 5 \end{pmatrix}$$
A
Last week we found A⁻¹ and it was
Last week we found A⁻¹ and it was

$$A^{-1} = \begin{pmatrix} 2 & -3 & 1 \\ 4/3 & -2 & 1 \\ -5/3 & 3 & -1 \end{pmatrix}$$
Multipy both sides of by A⁻¹
on the left to yet

$$\begin{pmatrix} 2 & -3 & 1 \\ -5/3 & 3 & -1 \end{pmatrix} \begin{pmatrix} 3 & 0 & 3 \\ 1 & 1 & 2 \\ -2 & 3 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 & -3 & 1 \\ 4/3 & -2 & 1 \\ -5/3 & 3 & -1 \end{pmatrix} \begin{pmatrix} 9 \\ -4 \\ 5 \end{pmatrix}$$
A⁻¹A = I_3

We get

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} X \\ 9 \\ Z \end{pmatrix} = \begin{pmatrix} 2 \cdot 9 + (-3)(-9) + (1)(5) \\ \frac{4}{5} \cdot 9 + (-2)(-9) + (1)(5) \\ -\frac{5}{3} \cdot 9 + (3)(-9) + (-1)(5) \end{pmatrix}$$

I₃

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 35 \\ 25 \\ -32 \end{pmatrix}$$

Thus, the answer to the system (x) is x = 35, y = 25, z = -32.

Topic 5 - Determinants The determinant will allow Vs to detect if an nxn matsix has an inverse.

Def: Let A be an nxn matrix. The matrix Azi is defined to be the (n-1)×(n-1) matrix obtained by deleting row i and column J from A.

 $\underbrace{E_{X;}}_{A=\begin{pmatrix}1&2&5\\4&5&6\\7&8&q \end{pmatrix} }$

 $A_{23} = \begin{pmatrix} 1 & 2 \\ 7 & 8 \end{pmatrix} + \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$ remove row 2 4 column 3 $A_{11} = \begin{pmatrix} 5 & 6 \\ 8 & 9 \end{pmatrix} + \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$ Def: Let A be an nxn Matrix. Let aij be the entry in row i and column J. The determinant of A, denoted by det(A),

is defined as follows: () If n = 1 and $A = (a_{11})$ then det $(A) = a_{11}$ (2) If n=2 and $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$ then $det(A) = a_{11}a_{22} - a_{12}a_{21}$ $\begin{pmatrix} \alpha_{11} & \alpha_{12} \\ \alpha_{21} & \alpha_{22} \end{pmatrix}$ 3 IF NZ3 then pick any column j to "expand on" and define $det(A) = \sum_{i=1}^{n} (-1)^{i+j} \cdot a_{ij} \cdot det(A_{ij})$ sums over the rows i

column j is fixed

Note: In step 3 above you cun instead pick a row i to expand on and then $det(A) = \hat{\leq} (-1)^{i+j} \cdot a_{ij} \cdot det(A_{ij})$ sums over columns j j=1 row i is fixed

Note: It doesn't matter what row or column you pick in Step 3. You'll get the same answer in the end Notation: Another notation for determinants is bars like this $det \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} = \begin{vmatrix} 1 & 2 \\ 3 & 4 \end{vmatrix}$

$$\underline{x:} \quad det(3) = 3$$

E

$$\frac{Ex:}{det} \begin{pmatrix} 1 & 5 \\ -2 & 6 \end{pmatrix}$$

= (1)(6) - (5)(-2)
= 6 + 10
= 16

$$\frac{E \times :}{A} = \begin{pmatrix} 3 & 1 & 0 \\ -2 & -4 & 3 \\ 5 & 4 & -2 \end{pmatrix}$$
Calculate det (A)

Let's pick column j=3 to expand on.

$$det(A) = \sum_{i=1}^{3} (-1) \cdot \alpha_{i3} \cdot det(A_{i3})$$

$$\hat{\lambda} = 1$$

$$= (-1)^{1+3} \cdot \alpha_{13} \cdot \det(A_{13}) \leftarrow (\bar{x}=1)^{1+3} + (-1)^{2+3} \cdot \alpha_{23} \cdot \det(A_{23}) \leftarrow (\bar{x}=2)^{1+3} + (-1)^{3+3} \cdot \alpha_{33} \cdot \det(A_{33}) \leftarrow (\bar{x}=3)^{1+3} + (-1)^{3+3} \cdot (\bar{x}=3)^{1+3} + (-1)^{3+3} + (-1)$$

$$A = \begin{pmatrix} 3 & 1 & 0 \\ -2 & -4 & 3 \\ 5 & 4 & -2 \end{pmatrix}$$

 $= (1)(0) \cdot \begin{vmatrix} -2 & -4 \\ 5 & 4 \end{vmatrix} = \begin{pmatrix} -2 & -4 \\ -2 & -4 \\ 5 & 4 & -2 \end{vmatrix}$ $+(-1)(3)\cdot \begin{vmatrix} 3 & 1 \\ 5 & 4 \end{vmatrix} \neq \begin{pmatrix} 3 & 1 \\ -2 & -4 & -2 \\ 5 & 4 & -2 \end{vmatrix}$ $+(1)(-2)\cdot \begin{vmatrix} 3 & 1 \\ -2 & -4 \end{vmatrix} = \begin{pmatrix} 3 & 1 \\ -2 & -4 \end{vmatrix}$

= () $-3 \cdot \left[(3)(4) - (1)(5) \right]$ $-2 \cdot \left[(3 \cdot (-4) - (1) \cdot (-2) \right]$ = -3[7] - 2[-10] = (-1)

PICTURE WAY TO FIND (-1) TI $\begin{pmatrix} (-1)^{1+1} & (-1)^{1+2} & (-1)^{1+3} \\ (-1)^{2+1} & (-1)^{2+2} & (-1)^{2+3} \\ (-1)^{5+1} & (-1)^{2+2} & (-1)^{3+3} \end{pmatrix} = \begin{pmatrix} 1 & -1 & 1 \\ -1 & -1 & -1 \\ 1 & -1 & 1 \end{pmatrix}$ We expanded COTUMN Z