

**Linear Algebra**

- (L1) Let  $V$  be a vector space over a field  $\mathbb{F}$ . Let  $W$  be a subspace of  $V$ . Fix an element  $v_0 \in V$ . Define the set  $W_0 = \{v_0 + w : w \in W\}$ . Prove that  $W_0$  is a subspace of  $V$  if and only if  $v_0 \in W$ .

**Answer:** Assume  $W_0$  is a subspace. Then,  $\vec{0} \in W_0$ . That is, there exists  $w \in W$  such that  $\vec{0} = v_0 + w$ . So,  $v_0 = -w \in W$ . Conversely, if  $v_0 \in W$  then  $W_0 \neq \emptyset$ :  $v_0 = v_0 + \vec{0} \in W_0$ . And if  $w, w' \in W$ ,  $(v_0 + w) + (v_0 + w') = v_0 + (w + v_0 + w') \in W_0$ . Therefore,  $W_0$  is a subspace of  $V$ .

- (L2) Let  $V$  be the real vector space of real functions spanned by  $\{1, x, e^x\}$ , and let  $h : V \rightarrow V$  be defined by  $h(f) = f - f'$  for all  $f \in V$ , that is,  $h(f)$  is  $f$  minus its derivative. No need to prove that  $h$  is a linear function.

- (1) What is the dimension of  $V$ ?
- (2) Find a basis for the space  $\ker h = \{f \in V : h(f) = 0\}$ .
- (3) Find a basis for the space  $\text{im } h = \{h(f) : f \in V\}$ .

**Answer:**

- (1) We show that  $\{1, x, e^x\}$  is linearly independent and hence  $\dim V = 3$ . Suppose that  $c_1 + c_2x + c_3e^x = 0$  for some  $c_1, c_2, c_3 \in \mathbb{R}$ . Plugging in  $x = -1$ ,  $x = 0$  and  $x = 1$  into this equation gives the system

$$\begin{aligned} c_1 - c_2 + c_3e^{-1} &= 0 \\ c_1 + c_3 &= 0 \\ c_1 + c_2 + c_3e &= 0 \end{aligned}$$

which can be solved to give  $c_1 = c_2 = c_3 = 0$ .

Or, since differentiation is a linear function, setting  $x = 0$  into  $c_1 + c_2x + c_3e^x = 0$  and the first and second derivatives of this equation gives  $c_1 + c_3 = 0$ ,  $c_2 + c_3 = 0$  and  $c_3 = 0$ , which is even easier to solve to get  $c_1 = c_2 = c_3 = 0$ .

- (2) If  $f = c_1 + c_2x + c_3e^x$  for some  $c_1, c_2, c_3 \in \mathbb{R}$ , then  $h(f) = (c_1 + c_2x + c_3e^x) - (c_2 + c_3e^x) = (c_1 - c_2) + c_2x$ . So  $f$  is in  $\ker h$  if and only if  $c_1 - c_2 = c_2 = 0$  if and only if  $c_1 = c_2 = 0$ , if and only if  $f = c_3e^x$  for some  $c_3 \in \mathbb{R}$ . So a basis for  $\ker h$  is  $\{e^x\}$ .
- (3) Since, from above,  $h(f) = (c_1 - c_2) + c_2x$ ,  $\{1, x\}$  is a basis for  $\text{im } h$ .

- (L3) Let  $T$  be an arbitrary linear operator on a vector space  $V$ , and let  $\lambda$  and  $\mu$  be two distinct eigenvalues of  $T$ .

- (a) Prove or disprove: If  $v$  is an eigenvector of  $T$  with eigenvalue  $\lambda$ , and  $w$  is an eigenvector of  $T$  with eigenvalue  $\mu$ , then  $v + w$  is an eigenvector of  $T$ .
- (b) Prove or disprove: If  $v$  and  $w$  are eigenvectors of  $T$  with eigenvalue  $\lambda$ , then  $v + w$  is an eigenvector of  $T$ .

**Answer:** The statement in (a) is false. For instance, if  $V = \mathbb{R}^2$  and  $T(x, y) = (x, 2y)$ , then  $(1, 0)$  has eigenvalue 1, and  $(0, 1)$  has eigenvalue 2. But  $(1, 0) + (0, 1) = (1, 1)$ , and  $(1, 1)$  is not an eigenvector since  $T(1, 1) = (1, 2)$  is not a scalar multiple of  $(1, 1)$ .

But (b) is true:  $T(v + w) = Tv + Tw = \lambda v + \lambda w = \lambda(v + w)$ , so  $v + w$  is an eigenvector with eigenvalue  $\lambda$ .

## Groups

(G1) Let  $G = \mathbb{Z}_4 \times \mathbb{Z}_6$  and  $H = \langle (2, 2) \rangle$ . What familiar group is  $G/H$  isomorphic to?

**Answer:** We have  $|G| = 24$  and  $|H| = 6$ , and so  $|G/H| = 4$ . Hence  $G/H$  is isomorphic to  $\mathbb{Z}_4$  or  $\mathbb{Z}_2 \times \mathbb{Z}_2$ . The elements of  $G/H$  are

$$\begin{aligned} H &= \{(0, 0), (2, 2), (0, 4), (2, 0), (0, 2), (2, 4)\} \\ (1, 0) + H &= \{(1, 0), (3, 2), (1, 4), (3, 0), (1, 2), (3, 4)\} \\ (1, 1) + H &= \{(1, 1), (3, 3), (1, 5), (3, 1), (1, 3), (3, 5)\} \\ (0, 1) + H &= \{(0, 1), (2, 3), (0, 5), (2, 1), (0, 3), (2, 5)\} \end{aligned}$$

Since  $(1, 0) + (1, 0) = (2, 0) \in H$ ,  $(1, 1) + (1, 1) = (2, 2) \in H$  and  $(0, 1) + (0, 1) = (0, 2) \in H$ , all nonidentity elements of  $G/H$  have order 2 and so  $G/H \cong \mathbb{Z}_2 \times \mathbb{Z}_2$ .

(G2) Let  $G$  be a group. For  $x, y \in G$ , recall that  $x$  is *conjugate* to  $y$  in  $G$  if there exists  $g \in G$  such that  $y = gxg^{-1}$ . We will write  $x \sim y$  to denote that  $x$  is conjugate to  $y$  in  $G$ . Prove that the relation “ $\sim$ ” is an equivalence relation on  $G$ .

**Answer:** Let  $x, y, z \in G$ . The relation is reflexive because  $1x1^{-1} = x$ , so  $x \sim x$ . If  $x \sim y$ , then  $y = gxg^{-1}$  for some  $g$ , so  $x = g^{-1}y(g^{-1})^{-1}$ , and so  $y \sim x$ ; thus the relation is symmetric. And if  $x \sim y$  and  $y \sim z$ , then  $y = gxg^{-1}$  and  $z = hyh^{-1}$  for some  $g, h$ , so  $z = hgxg^{-1}h^{-1} = (hg)x(hg)^{-1}$ , and so  $x \sim z$ ; thus the relation is transitive.

(G3) Let  $G$  be an Abelian group. Let  $H$  be the set of elements of  $G$  with finite order; that is,  $H = \{g \in G : |g| < \infty\}$ . Prove that  $H$  is a subgroup of  $G$ .

**Answer:** First of all, the identity of  $G$  has order 1, so it is in  $H$ . Now let  $g, h \in H$ . This means that  $g$  and  $h$  have finite order; say  $|g| = m$  and  $|h| = n$ . Then  $gh$  has finite order, because  $(gh)^{mn} = g^{mn}h^{mn}$  (since  $G$  is Abelian), and  $g^{mn} = (g^m)^n = 1$  and  $h^{mn} = (h^n)^m = 1$ . Thus  $gh \in H$ . Finally,  $g^{-1}$  has the same order as  $g$ , so  $g^{-1} \in H$ .

## Synthesis

(S1) Find a subgroup of  $GL_2(\mathbb{C})$  that is isomorphic to  $\mathbb{Z}_4$ .

**Answer:** There are lots of answers. For example,

$$\begin{aligned} &\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \right\} \\ &\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} i & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} -i & 0 \\ 0 & 1 \end{bmatrix} \right\} \end{aligned}$$

(S2) Let  $H$  be the set of all matrices in  $GL_2(\mathbb{R})$  with integer entries. Is  $H$  a subgroup of  $GL_2(\mathbb{R})$ ? Prove your answer.

**Answer:** No, because it is not closed under inverses: for instance, if  $A = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$ ,

then  $A \in H$  but  $A^{-1} = \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \notin H$ .

(S3) Let  $n$  be a nonnegative integer. Recall that  $\mathbb{R}^*$  is the group of non-zero real numbers under multiplication. Define  $\phi : GL_n(\mathbb{R}) \rightarrow \mathbb{R}^*$  by  $\phi(A) = \det(A)$ , the determinant of  $A$ .

(a) Use a property of determinants to explain why  $\phi$  is a homomorphism.

(b) Determine  $\ker(\phi)$  and  $\text{im}(\phi)$ .

(c) Based on your answers to (a) and (b), use the First Isomorphism Theorem to make a statement involving a quotient group of  $GL_n(\mathbb{R})$ .

**Answer:** (a) Note that  $\phi(A \cdot B) = \det(A \cdot B) = \det(A) \cdot \det(B) = \phi(A) \cdot \phi(B)$ . Therefore,  $\phi$  is a homomorphism.

(b)  $\ker(\phi) = \{A \in GL_n(\mathbb{R}) : \det(A) = 1\} = SL_n(\mathbb{R})$ .

$\text{im}(\phi) = \mathbb{R}^*$ , because, for each  $r \in \mathbb{R}^*$ , the diagonal matrix  $A$  with entries  $r, 1, 1, \dots, 1$  has determinant  $r$ , so  $\phi(A) = r$ .

(c) By the First Isomorphism Theorem,  $GL_n(\mathbb{R})/\ker(\phi)$  is isomorphic to  $\mathbb{R}^*$ .