

Department of Mathematics
California State University Los Angeles

Master's Degree Comprehensive Examination in

NUMERICAL ANALYSIS
SPRING 2023

Instructions:

- Do exactly **two problems from Part A AND two problems from Part B**. If you attempt more than two problems in either Part A or Part B, and do not clearly indicate which two are to count, only the first two problems will be counted towards your grade.
 - No notes, books, calculators, internet or cell phones are allowed.
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PART A: Do only **TWO** problems

1. Given a 3×3 matrix

$$A = \begin{pmatrix} 2 & 0 & k \\ 0 & 2 & k \\ k & k & 2 \end{pmatrix} \quad \text{with } k \in \mathbb{R}.$$

- (a) Determine *all* values k for which A is
 - i. [4 pts] strictly diagonally dominant.
 - ii. [4 pts] orthogonal.
 - iii. [4 pts] positive definite.
 - (b) [7 pts] Find the spectral radius of the Gauss-Seidel iteration matrix for solving $A\mathbf{x} = \mathbf{b}$. Then determine *all* values k for which the Gauss-Seidel iteration converges.
 - (c) [6 pts] Perform one step of the Gauss-Seidel iteration for solving $A\mathbf{x} = \mathbf{b}$ with $k = 1$, and $\mathbf{b} = (1, 2, 3)^T$. Use the initial guess $\mathbf{x}_0 = (0, 0, 0)^T$.
2. Given $A \in \mathbb{C}^{n \times n}$. Assume that the eigenvalues of A satisfy $|\lambda_1| > |\lambda_2| > \cdots > |\lambda_n|$.
- (a) [6 pts] Describe the power method to find λ_1 and its corresponding eigenvector. Does the power method always converge for any initial vector \mathbf{q}_0 ? Explain your answer.

- (b) [6 pts] Show that the convergence is linear.
- (c) [4 pts] Give one advantage and one disadvantage of the power method, in comparison to the QR method.
- (d) [3 pts] Describe briefly how Rayleigh Quotient Iteration improves rate of convergence for power method.
- (e) [6 pts] Perform one steps of Rayleigh Quotient Iteration on matrix $\begin{pmatrix} 2 & -2 \\ -3 & 1 \end{pmatrix}$ with initial vector $\mathbf{q}_0 = (1, 0)^T$.

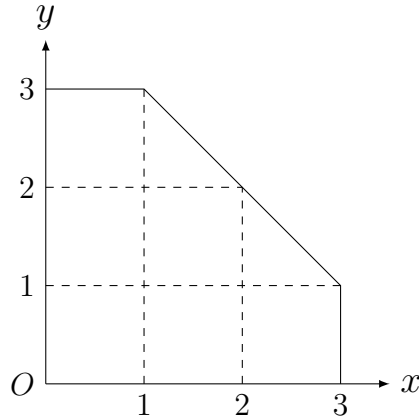
3. Consider the linear system $A\mathbf{x} = \mathbf{b}$ where

$$A = \begin{pmatrix} 4 & 0 & 3 \\ 4 & 1 & 2 \\ 8 & 3 & 5 \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} 4 \\ 6 \\ 14 \end{pmatrix}.$$

- (a) [8 pts] Use Gaussian elimination with partial pivoting to write the matrix A in the form $PA = LU$, where P is a permutation matrix, L is a unit lower triangular matrix and U is an upper triangular matrix.
- (b) [6 pts] Use the result from (a) to solve the linear system $A\mathbf{x} = \mathbf{b}$.
- (c) [5 pts] Can the above system be solved using Gaussian elimination without pivoting? Explain your answer.
- (d) [3 pts] Given one reason why Gaussian elimination with partial pivoting is preferred in practice over Gaussian elimination without pivoting.
- (e) [3 pts] Briefly describe the complete pivoting strategy and its performance in comparison to the partial pivoting.

PART B: Do only **TWO** problems

1. Consider the PDE $u_{xx} + 3u_{yy} = 6$ with boundary values $u(x, y) = 2x^2 + y^2$ defined on the region R shown below:



- (a) [5 pts] Find the maximum value of u attained within the region R . At what point(s) is this maximum value attained?
- (b) [8 pts] Suppose that we approximate this PDE by the usual 5-point scheme on a square mesh with $\Delta x = \Delta y = h = 1$. Write down the resulting system of linear equations in matrix form $A\mathbf{u} = \mathbf{b}$.
- (c) [5 pts] Derive the local truncation error for the 5-point scheme that you used in part (b).
- (d) [7 pts] Now suppose that the boundary condition along $y = 0$ is replaced by $u_y(x, 0) = 1$ for $0 < x < 3$. Write a second order accurate finite difference equation to approximate the solution at the point $(2, 0)$ in terms of $u(1, 0)$ and $u(2, 1)$.
2. Consider the PDE

$$\begin{aligned} u_{xx} + xu_{xy} - 2x^2u_{yy} &= 0 \\ u(x, 0) &= x^2, \quad -\infty < x < \infty \\ u_y(x, 0) &= 0, \quad -\infty < x < \infty. \end{aligned}$$

- (a) [3 pts] Determine all values of x for which the given PDE is hyperbolic.
- (b) [4 pts] Determine the slope of the characteristic curves for the PDE at a point (x, y) .
- (c) [6 pts] Find the exact values of the coordinates of the point of intersection $R(x_R, y_R)$, where $y_R > 0$, of the characteristic curves through the points $P(2, 0)$ and $Q(4, 0)$.

- (d) [3 pts] State the CFL condition that gives the stability condition for the numerical scheme used to approximate the above PDE.
- (e) [4 pts] Suppose we approximate the given PDE by a consistent explicit finite difference scheme with $h = k = 1$. Does the scheme converge at the point R you found in part (c)? Explain your reasoning.
- (f) [5 pts] Derive a consistent finite difference approximation for the term xu_{xy} that is $O(h, k^2)$. You need not prove that your approximation is consistent.

3. Consider the PDE

$$\begin{aligned} u_t &= u_{xx}, \quad 0 \leq x \leq 1, \quad t > 0 \\ u(x, 0) &= x(1-x), \quad 0 \leq x \leq 1 \\ u(0, t) &= 1, \quad u(1, t) = t, \quad t > 0. \end{aligned}$$

Suppose we approximate the above PDE by a finite difference scheme

$$-r(1-\theta)u_{i-1,j+1} + (1+2r\theta)u_{i,j+1} - r(1-\theta)u_{i+1,j+1} = r\theta u_{i-1,j} + (1-2r(1-\theta))u_{i,j} + r\theta u_{i+1,j},$$

where $r = k/h^2$, $k = \Delta t$, $h = \Delta x$, $u_{i,j}$ approximates $U(ih, jk)$, and θ is a parameter with $0 \leq \theta \leq 1$.

- (a) [3 pts] Find all value(s) of θ for which the scheme is implicit.
- (b) [10 pts] Let $h = 1/4$, $k = 1/16$ (that is, $r = 1$) and $\theta = 1/2$. Find the matrices A, B and vector \mathbf{f}_j such that

$$A\mathbf{u}_{j+1} = B\mathbf{u}_j + \mathbf{f}_j,$$

where $\mathbf{u}_j = (u_{1,j}, u_{2,j}, \dots, u_{N-1,j})^T$.

- (c) [6 pts] Now let $\theta = 1$. Perform von Neumann analysis to find the value(s) of r for which the scheme is stable.
- (d) [3 pts] Give an example of a stable scheme that is consistent with the above PDE but not convergent, if any. If there is none, explain why.
- (e) [3 pts] Give an example of a consistent scheme that is second order accurate in both x and t , if any. If there is none, explain why.